

Vehicle control method involves discarding computation result or interrupting computation if additional forces occur that can alter force equilibrium in vehicle's longitudinal direction

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Abstract of DE19859022

The method involves evaluating force equilibrium in the longitudinal direction during a dynamic operating process and computing at least one non-measured operating parameter, depending on which the vehicle is controlled. The computation result is discarded or the computation interrupted if an operating situation occurs in which additional forces occur that can alter the equilibrium in the longitudinal direction. An Independent claim is also included for an arrangement for controlling a vehicle.